

# Software architecture for reactive systems: A short look at model checking (revisions)

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# Model checking

Recall “Especificação e Modelação”:

- **Modelling** reactive systems – Kripke structures and ~~Petri-Nets~~ SMV
- **Specification** – Temporal logics (LTL and ~~CTL/CTL\*~~)
- **Verification** – Check if a formula holds in a system

**SMV model checker**

# What we will see

- **Labelled transition systems (LTS)** as Kripke structures
  - **Process algebra** (not Petri-Nets SMV) to define LTS
  - **mCRL2** toolset to model (not SMV)
  - Equivalence of LTS
- **Modal logics** – generalising temporal logics (CTL\*,CTL,LTL)
- Using **mCRL2** toolset to **verify** properties
  
- Later: **Timed-automata** and **UPPAAL** model checker (CTL)

# Model

$\mathfrak{M}, w \models \phi$  – what does it mean?

## Model definition

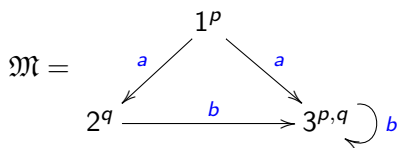
A **model** for the language is a pair  $\mathfrak{M} = \langle \mathfrak{F}, V \rangle$ , where

- $\mathfrak{F} = \langle W, \{R_m\}_{m \in \text{MOD}} \rangle$   
is a **Kripke frame**, ie, a non empty set  $W$  and a family  $R_m$  of **binary relations** (called *accessibility relations*) over  $W$ , one for each modality symbol  $m \in \text{MOD}$ . Elements of  $W$  are called **points, states, worlds** or simply **vertices** in directed graphs.
- $V : \text{PROP} \rightarrow \mathcal{P}(W)$  is a **valuation**.

## Kripke structures from last semester

- $\text{MOD} = \{\mathbf{1}\}$
- $(S, I, R, L)$  where  $S = W$ ,  $I = \{w\}$ ,  $R = R_1$ ,  $L = V$
- $\mathfrak{F} = \langle W, R \rangle$  instead of  $\mathfrak{F} = \langle W, \{R_m\}_{m \in \text{MOD}} \rangle$

## Example



$$W = \{1, 2, 3\}$$

$$MOD = \{a, b\}$$

$$R_a = \{(1, 2), (1, 3)\}$$

$$R_b = \{(2, 3), (3, 3)\}$$

$$V = \{1 \mapsto \{p\},$$

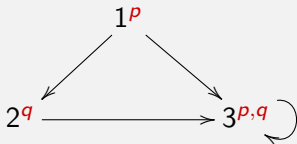
$$2 \mapsto \{q\},$$

$$3 \mapsto \{p, q\}\}$$

- $\mathfrak{M}, 1 \models p$   
means  $p$  holds in state 1
- $\mathfrak{M}, 2 \models [b]p$   
means  $p$  holds in every  
state reachable with  $b$   
from 2.

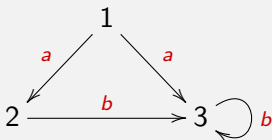
# Key differences

## Before



- emphasize on **states** - desired/forbidden states
- **SMV language** to generate models
- $\mathfrak{M}, 1 \models p$  ,  $\mathfrak{M}, 1 \models FGp$

## Now



- emphasize on **actions** - desired/forbidden sequences
- **Process algebra** to generate models
- $\mathfrak{M}, 2 \models [a] \text{ false}$