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SPECIFICATION AND MODELING

ELECTRUM OVERVIEW

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TRASH



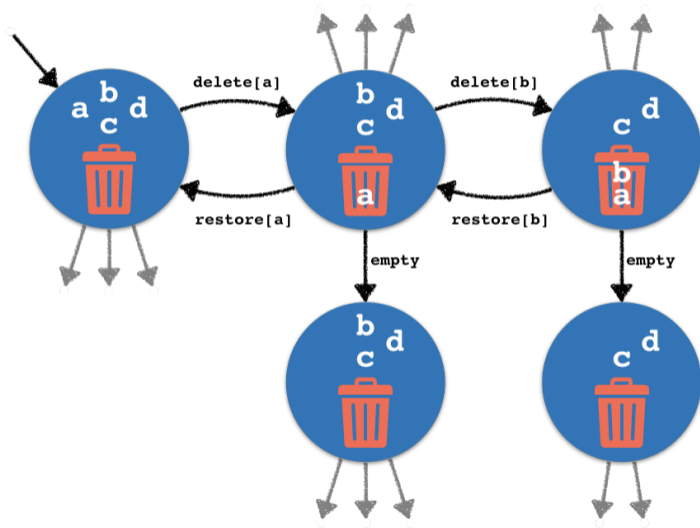
Design a trash component such that:

- A deleted file can still be restored if the trash is not emptied

TASKS

- Design of the structure and behavior (operations) of the component
- Validate this design by simulation
- Elicit and verify expected properties

TRANSITION SYSTEMS



STATE

- A *state* is an assignment of values to variables
- In abstract design, it is useful to rely on standard mathematical structures to describe states

Alloy

- Values are sets and relations
- Inhabited by (tuples of) uninterpreted *atoms*
- Sets are declared with the **sig** keyword

Electrum

- Mutable sets (state variables) are also declared with the **var** keyword

TRASH STATE



```
var sig File {}
```

```
var sig Trash in File {}
```

EXPLICIT MODELING OF TRANSITION SYSTEMS

- A transition system can be modeled explicitly:
 - ▶ Define which are the initial states
 - ▶ Define how the next state(s) can be obtained from the current one
- In formal software design, all states are usually required to always have at least one successor

SMV

The transition system is explicitly modeled with a DSL

The verification tool can detect *deadlocks*

IMPLICIT BEHAVIOR SPECIFICATION

- The behaviour of a transition system can be abstracted by its set of *infinite traces*
 - ▶ This is known as a *linear model of time*
- This set of traces can be modeled implicitly:
 - ▶ By a property that “recognises” the valid traces among all possible sequences of states
 - ▶ This property can be specified with a *linear temporal logic*
 - ▶ Ideally combined with a first order logic to specify properties of states

Electrum

The transition system is implicitly modeled with a linear temporal logic specification enclosed in a **fact**

The (infinite) traces satisfying this specification are also known as *instances*

FIRST ORDER LOGIC

Alloy	Math
not	\neg
and	\wedge
or	\vee
implies	\rightarrow
all $x : e \mid p$	$\forall x \cdot x \in e \rightarrow p$
some $x : e \mid p$	$\exists x \cdot x \in e \wedge p$

SET OPERATORS

Alloy	Math
in	\subseteq
+	\cup
&	\cap
-	\setminus
no e	$e = \emptyset$
some e	$e \neq \emptyset$

LINEAR TEMPORAL LOGIC

Electrum	Meaning
always p	p is always true from now on
after p	p is true in the next state
once p	p was once true
...	...
e'	the value of e in the next state

AN ELECTRUM PATTERN FOR BEHAVIOR SPECIFICATION

```
fact init { ... }
```

```
fact transitions { always (event1 or event2 or ...) }
```

- The specification of every event typically involves:
 - ▶ *Guard* - a state formula that checks if the event can occur
 - ▶ *Effect* - a formula with primes specifying how some state variables change
 - ▶ *Frame* - a formula with primes stating what does *not* change

TRASH BEHAVIOR

```
fact init { no Trash }
```

```
fact transitions {  
  always (  
    // delete file  
    (some f: File | f not in Trash and           -- guard  
      Trash' = Trash + f and                   -- effect  
      File' = File) or                          -- frame  
  
    // restore file  
    ... or  
    // empty trash  
    ...  
  )  
}
```

TRASH BEHAVIOR REFACTORED WITH PREDICATES

```
pred delete[f : File] {  
    f not in Trash  
    Trash' = Trash + f  
    File' = File  
}  
pred restore[f : File] { ... }  
pred empty { ... }  
  
fact transitions {  
    always (  
        (some f: File | delete[f] or restore[f]) or empty  
    )  
}
```

SIMULATION

- Models include analysis commands
- A **run** command asks for an instance (checking the consistency of the facts)
- Further instances can be obtained by an interactive exploration mode akin to simulation
- All commands have a scope that bounds the size of the signatures
- The default is 3, but can be changed with the **for** keyword



TRASH BEHAVIOR FIXED

```
pred delete[f : File] { ... }
pred restore[f : File] { ... }
pred empty { ... }
pred do_nothing {
  Trash' = Trash
  File' = File
}

fact transitions {
  always (
    (some f: File | delete[f] or restore[f]) or empty or do_nothing
  )
}
```

ASSERTIONS

- In Electrum, the same first order temporal logic is used for
 - ▶ modeling
 - ▶ specification of expected properties – *assertions*
- The latter can be enclosed in named **assert** paragraphs

EXAMPLE ASSERTIONS

```
assert restoreAfterDelete {  
  -- Every restored file was once deleted  
  always (all f : File | restore[f] implies once delete[f])  
}
```

```
assert deleteAll {  
  -- If the trash contains all files and is emptied  
  -- then no files will ever exist afterwards  
  always ((File in Trash and empty) implies always no File)  
}
```

VERIFICATION

- **check** commands are used to verify assertions
- The verification is fully automatic, but limited to the specified scope
- The set of counter-examples can also be explored like instances



FIXED ASSERTION

```
assert deleteAll {  
  -- If the trash contains all files and is emptied  
  -- then no files will ever exist afterwards  
  always ((File in Trash and empty) implies after (always no File))  
}
```